Stress-strength model for skew-normal distributions

A. Azzalini, M. Chiogna

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Dipartimento di Scienze Statistiche
Università degli Studi
Via C. Battisti 241-243
35121 Padova

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1 Introduction

The stress-strength problem  The stress-strength problem, as it is called in statistical quality control, is concerned with evaluation of the probability that the strength of a given material is larger than the stress which is applied to that material. Phrased in probability terms, the previous question leads to evaluation of

$$\rho = P(Y_2 < Y_1).$$  \hspace{1cm} (1)

for two random variables $Y_1$ and $Y_2$, representing strength and stress, respectively.

The problem comes actually in two parts: (i) given some assumptions on the distribution of the variables, provide an expression for $\rho$; (ii) given a set of data which are supposed to fulfill these assumptions, estimate $\rho$, both in the form of point estimation and of interval estimation.

Early literature in this area has focussed on the normal assumption for $Y_1$ and $Y_2$. This includes Church & Harris (1970) and Downton (1973) who have provided basic results. A number of other distributions and other variants of the problem have been discussed since then. A recent introductory account on this topic is given by Blischke & Prabhatkaran Murthy (2000, p. 276–8).

The purpose of this note is to examine the above problem when all or some of the underlying probability distributions are of skew-normal type; a brief summary of the skew-normal distribution is provided below.

The skew-normal distribution  A random variable $Z$ is said to have a skew-normal distribution if it is continuous and its density function is

$$\phi(z; \lambda) = 2\phi(z) \Phi(\lambda z), \hspace{1cm} (z \in \mathbb{R}), \hspace{1cm} (2)$$

for some parameters $\lambda \in \mathbb{R}$; here $\phi(z)$ and $\Phi(z)$ denote the $N(0,1)$ density and distribution function, respectively. The shape of (2) is skewed to the right or to the left, according to the sign of $\lambda$; for $\lambda = 0$ we obtain a standard normal density. In fact, (2) refers to the 'standard' skew-normal distribution; if a linear transform $Y = \xi + \omega Z$ is considered, we shall then say that $Y$ has distribution $SN(\xi, \omega^2, \lambda)$.  

1
Various results about (2) are given by Azzalini (1985); see also Azzalini and Capitanio (1999) and references therein. For our purposes, we only recall that its distribution function \( \Phi(z; \lambda) \) enjoys the following properties

\[
\begin{align*}
\Phi(-z; \lambda) &= 1 - \Phi(z; -\lambda), \\
\Phi(z; \lambda) &= \Phi(z) - 2T(z, \lambda), \\
\Phi(0; \lambda) &= \frac{1}{2} - \frac{1}{\pi} \arctan \lambda, \\
\Phi(z; 0) &= \Phi(z)
\end{align*}
\]

where \( T(z, \lambda) \) is the function studied by Owen (1956). A computer routine to evaluate \( T(z, \lambda) \) has been given by Young and Minder (1974), subsequently improved by various authors.

## 2 Probability results

Assume that the observed variables \( Y_1, Y_2 \) are of type

\[
Y_i = \xi_i + \omega_i Z_i, \quad Z_i \sim SN(\lambda_i) \quad (i = 1, 2)
\]

and \( Y_1 \) is independent of \( Y_2 \). Under these assumptions,

\[
\rho = P(\xi_2 + \omega_2 Z_2 < \xi_1 + \omega_1 Z_1) = E_{Z_1}\{P(\xi_2 + \omega_2 Z_2 < \xi_1 + \omega_1 Z_1 | Z_1)\} = E_{Z_1}\left\{ \Phi\left( \frac{\xi_1 - \xi_2 + \omega_1 Z_1}{\omega_2 \lambda_2} \right) | Z_1 \right\}.
\]

An explicit expression of this quantity in the general case does not seem feasible. However, if one relaxes the assumption of skew-normality for one component, then computation follows easily from Proposition 2 of Chiogna (1998), which for convenience we reproduce here, up to inessential modifications.

**Proposition 1** If \( Z \sim SN(\lambda) \) and \( U \sim N(0, 1) \), then

\[
E(\Phi(hU + k; \lambda)) = \Phi(k/\sqrt{1 + h^2}; m(h, \lambda)),
\]

\[
E(\Phi(hZ + k)) = \Phi(k/\sqrt{1 + h^2}; m(1/h, -\lambda)),
\]

where

\[
m(h, \lambda) = \frac{\lambda}{\sqrt{1 + h^2(1 + \lambda^2)}}.
\]

If we assume \( \lambda_1 = 0 \) in (4), we can make use of the first statement of the above proposition and obtain

\[
\rho = \Phi(\Delta; \lambda) = \Phi(\Delta) - 2T(\Delta, \lambda)
\]
where
\[ \Delta = \frac{\xi_1 - \xi_2}{\sqrt{\omega_1^2 + \omega_2^2}}, \quad \Lambda = m(\omega_1/\omega_2, \lambda_2). \]

Notice the following facts. If \( \lambda_2 = 0 \), then also \( \Lambda = 0 \) and the above expression becomes \( \rho = \Phi(\Delta) \), the usual expression for the normal case. If we assume instead that \( \lambda_2 = 0 \) and \( \lambda_1 \) is unrestricted, then we have the same development as above but (4) is now computed using the second statement of Proposition 1, leading to
\[ \rho = \Phi(\Delta, m(\omega_2/\omega_1, -\lambda_1)) \]

which is of the same type of the expression for the earlier case. Hence we do not need a special development, and in the following we shall concentrate on the case \( \lambda_1 = 0 \).

We turn now to consider the case when both \( \lambda_1 \) and \( \lambda_2 \) in (3) are unrestricted, but \( \xi_1 = \xi_2 \). Hence (4) now becomes
\[ \mathbb{E}_{Z_1}(\Phi(\omega_1/\omega_2, Z_1; \lambda_2) | Z_1) \]
and this is readily expressed using Proposition 3 of Chiogna (1998), which again is reproduced here up to inessential modifications.

**Proposition 2** If \( Z \sim SN(\lambda) \), then
\[ \mathbb{E}(\Phi(hZ; \beta)) = \frac{1}{2} - \frac{1}{\pi} \arctan \frac{m(h, \beta) - m(1/h, \lambda)}{m(h, \beta) + m(1/h, \lambda)}. \]

(6)

Hence we can write
\[ \rho = \frac{1}{2} - \frac{1}{\pi} \arctan \frac{m(h, \lambda_2) - m(1/h, \lambda_1)}{m(h, \lambda_2) + m(1/h, \lambda_1)}, \]

where \( h = \omega_1/\omega_2 \).

Evaluation of (1) in another special case has been considered by Gupta & Brown (2001); see in particular Section 4. The important difference in the assumptions is that \( (Z_1, Z_2) \) in their case follow a bivariate skew-normal distribution with correlated components. The multivariate skew-normal distribution has been studied by Azzalini & Dalla Valle (1996) and subsequently by Azzalini & Capitanio (1999).

### 3 Likelihood Inference

Consider the problem of statistical inference for \( \rho \) under the assumption of independent samples from \( Y_1 \) and from \( Y_2 \) to make inference on (5).

Since the context is outside the exponential family, UMVU estimation is not feasible and we consider then likelihood inference. Specifically, we replace the parameters in (5) by their MLE’s. Notice that, in the normal distribution case, Downton (1973) compares UMVU with other procedures including one which is MLE (although it is not recognised as such); see his \( r_1 \) in the one-sample case and a similar one in the two-sample case. These turn out to compare very favourably with UMVU.
For a generic parameter \( \psi \) denote by \( \hat{\psi} \) its MLE; similarly \( \hat{\lambda}, \bar{\lambda} \) are obtained by appropriate transformations of \( \Delta, \Lambda \). The estimate of (5) is then given by

\[
\hat{\beta} = \Phi(\hat{\lambda}; \bar{\lambda}) = \Phi(\hat{\lambda}) - 2\, T(\hat{\lambda}, \bar{\lambda}).
\]  

Also we shall use the notation \( \hat{\psi}_- \) and \( \hat{\psi}_+ \) to indicate \( \hat{\psi} - u_\alpha \) s.e.(\( \hat{\psi} \)) and \( \hat{\psi} + u_\alpha \) s.e.(\( \hat{\psi} \)) respectively, for an appropriate choice of the normal quantile \( u_\alpha \) such that \( \Phi(-u_\alpha) = \alpha/2 \), for a given choice of the confidence level \( 1 - \alpha \).

Confidence intervals of the form \((\hat{\beta}_-, \hat{\beta}_+)\) are not appropriate, since this may exceed the interval \((0, 1)\). More sensible choices are

I: \( (\Phi(\hat{\lambda}_-; \bar{\lambda}), \Phi(\hat{\lambda}_+; \bar{\lambda})) \),

II: \( (\Phi(\hat{\lambda}_-; \bar{\lambda}_+), \Phi(\hat{\lambda}_+; \bar{\lambda}_-)) \),

where the latter form is supported by the fact that \( \Phi(z; \lambda) \) is a decreasing function of \( \lambda \), for any fixed \( z \).

The effectiveness of these choices needs to be assessed by simulation methods. In particular we must consider: (i) bias of (7), (ii) variance of (7), and especially (iii) the associated actual level for procedures I and II, in comparison with the nominal level, To obtain the required standard errors we resort on asymptotic theory. Some points to keep in mind are as follows.

1. Standard errors are obtained via the Fisher information evaluated at the MLE's. Having to choose between observed and expected information, the first one seems preferable to avoid the numerical integrations involved by the other case. Furthermore, the use of observed instead of expected information is keeping with general considerations, such as those given e.g. by Efron & Hinkley (1978).

2. Small samples likelihood inference for the skew-normal distribution poses problems. This fact has emerged from the results of several people, variously focusing on the theoretical and the practical aspects; see Azzalini (1985), Chiogna (1997), Azzalini & Capitanio (1999, section 5), Pewsey (2000). It is then sensible to consider estimation of the parameter only when the sample size is not too small. As a crude guideline, \( n = 50 \) seems to be about the practical lower bound.

Let \( \theta_1 = (\xi_1, \omega_1) \) and \( \theta_2 = (\xi_2, \omega_2, \lambda_2) \). The observed Fisher information matrix for the parameter \( \theta = (\theta_1, \theta_2) \) has a block structure, because of the independence between the two samples. Denote by \( j_{ii}(\theta_i) \) the block corresponding to \( \theta_i, i = 1, 2 \). It is well know that

\[
j_{11}(\theta_1) = n \begin{pmatrix} 1/\omega_1^2 & 0 \\ 0 & 2/\omega_1^2 \end{pmatrix}
\]

which of course must be evaluated at \( \theta_1 = 0_1 \). As for \( j_{22}(\theta_2) \), the observed information matrix can be obtained from the formulae given in the appendix.

To obtain asymptotic variances (av) for \( \hat{\lambda} \) and \( \bar{\lambda} \), it is possible to resort on the multivariate \( \delta \)-method; for a standard account on this techniques, see for instance Schervish
(1995). By applying the δ-method one obtains:

\[ \text{av}(\hat{\lambda}) = \frac{1}{\omega_1^2 + \omega_2^2} \left\{ \frac{\omega_1^2}{n} \left( 1 + 2\delta^2 \omega_1^2 \right) + \sigma_{11} - 2\sigma_{12} \omega_2 \delta + \sigma_{22} \omega_2^2 \delta^2 \right\}, \]

\[ \text{av}(\tilde{\lambda}) = \left( \frac{\lambda_2^2}{\omega_2} \right)^{\frac{1}{2}} \left\{ n \frac{2\omega_1^2 \omega_2^2 \psi^2}{\delta^2} + \sigma_{22} \omega_2^2 \psi \tilde{\omega} + \sigma_{33} \tilde{\omega}^2 \right\}, \]

where \( \sigma_{ij} \) denotes the \((i,j)\) entry of \( J_{22}(\theta_2)^{-1} \), \( \delta = \Delta^2 / (\xi_2 - \xi_1) \), \( \psi = \lambda_2 (1 + \lambda_2^2) \) and \( \tilde{\omega} = \omega_2 (\omega_1^2 + \omega_2^2) \). Notice that \( \sigma_{ij}'s \) are terms of order \( 1/n \).

To perform simulations, it has been assumed that the parameters of \( Y_1 \) are known, in analogy with Curch & Harris (1970) and Downton (1973). Without loss of generality, it is assumed that \( Y_1 \) is distributed as a standard normal variate, so that \( \theta = (0, 1, \xi_2, \omega_2, \lambda_2) \). In this case, it is easily shown that previous expressions reduce to:

\[ \text{av}(\hat{\lambda}) = \frac{1}{1 + \omega_2^2} \left\{ \sigma_{11} - \frac{2\sigma_{12} \xi_2 \omega_2}{1 + \omega_2^2} + \frac{\sigma_{22} \xi_2^2 \omega_2^2}{1 + \omega_2^2} \right\}, \]

\[ \text{av}(\tilde{\lambda}) = \frac{1}{(1 + \omega_2^2 + \lambda_2^2)} \left\{ n \sigma_{22} (\lambda_2 (1 + \lambda_2^2)) + 2\sigma_{23} (\omega_2 (1 + \omega_2^2)) (\lambda_2 (1 + \lambda_2^2)) + \sigma_{33} (\omega_2 (1 + \omega_2^2))^2 \right\} \]

Simulation work has been carried out to evaluate the actual level achieved by methods I and II described above when they are used at the nominal level 95%; the outcome is summarised in Table 1. Each entry of the tables has been obtained from 1000 generated samples and the number of cases where the confidence interval covers the actual value of \( \rho \) is reported.

Inspection of the table indicates that the agreement to the nominal level is greater for small \( \lambda_2 \) and for large \( n \). Serious discrepancies from 95% are encountered when \( n = 50 \) and \( \lambda_2 = 10 \) or even 5. Indications are much more favourable is the other cases, especially for \( n = 200 \) and \( \lambda_2 = 2 \), and to some extent \( \lambda_2 = 5 \).

In interpreting these values, one must bear in mind that, in a number of industrial applications to measurements data, large asymmetries are not to be expected. In this sense, the bad entries for very large \( \lambda_2 \) must be down-weighted, and the overall picture emerging from the table is acceptable comfortable.

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Appendix

Log-likelihood function and derivatives for SN variates

Consider a random sample \( y_1, \ldots, y_n \) from \( SN(\xi, \omega^2, \lambda) \). Write

\[ y_i = \xi + \omega z_i, \quad Z \sim SN(0, 1, \lambda). \]
| $\rho$ | $0.90$ | $0.95$ | $0.99$ | $0.999$ | $n$ | 1 | 2 | 3 | 1 | 2 | 3 | 1 | 2 | 3 | 1 | 2 | 3 | 1 | 2 | 3 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| 0.00 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.01 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.02 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.03 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.04 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.05 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.06 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.07 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.08 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.09 | 5.0 | 2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |

Table 1: Estimated actual confidence levels for $\rho$ using methods I and II described in the text, multiplied by 1000.
Then the log-likelihood for $\mathbf{DP} = (\xi, \omega, \lambda)$ is

$$
\ell(\mathbf{DP}) = \sum_i \left( - \log \omega - \frac{1}{2} z_i^2 + \log(2\Phi(\lambda z_i)) \right) = -n \log \omega - \frac{1}{2} \sum z_i^2 + \sum \zeta_0(\lambda z_i)
$$

with partial derivatives

$$
\frac{\partial \ell}{\partial \xi} = \sum \{ -z_i + \lambda \zeta_1(\lambda z_i) \} (-1/\omega),
$$

$$
\frac{\partial \ell}{\partial \omega} = \sum \{ -z_i + \lambda \zeta_1(\lambda z_i) \} (-z_i/\omega) - n/\omega,
$$

$$
\frac{\partial \ell}{\partial \lambda} = \sum (z_i \zeta_1(\lambda z_i))
$$

Here $\zeta_0(x) = \log(2\Phi(x))$ and $\zeta_r(x)$ is its $r$-th derivative. The negative second derivatives of $\ell$ are:

$$
\frac{\partial^2 \ell}{\partial \xi^2} = \sum \{ 1 - \lambda^2 \zeta_2(\lambda z_i) \}/\omega^2,
$$

$$
\frac{\partial^2 \ell}{\partial \xi \partial \omega} = \sum \left\{ \frac{1 - \lambda^2 \zeta_2(\lambda z_i) z_i + z_i - \lambda \zeta_1(\lambda z_i)}{\omega^2} \right\},
$$

$$
\frac{\partial^2 \ell}{\partial \xi \partial \lambda} = \sum (\zeta_1(\lambda z_i) + \lambda z_i \zeta_2(\lambda z_i))/\omega,
$$

$$
\frac{\partial^2 \ell}{\partial \omega^2} = \sum \left\{ z_i^2 [3 - \lambda^2 \zeta_2(\lambda z_i)] - 2\lambda z_i \zeta_1(\lambda z_i) - 1 \right\}/\omega^2,
$$

$$
\frac{\partial^2 \ell}{\partial \omega \partial \lambda} = \sum (\zeta_1(\lambda z_i) + \lambda z_i \zeta_2(\lambda z_i)) z_i/\omega
$$

$$
\frac{\partial^2 \ell}{\partial \lambda^2} = -\sum z_i^2 \zeta_2(\lambda z_i)
$$

References


